

Approximation Algorithms using ILP

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- 6 Rectangle Stabbing Problem
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Introduction

- A problem is said to be **tractable** if there exists an algorithm for that problem whose worst case time complexity is a polynomial function in n (the input size).
- Otherwise, the problem is said to be **intractable**.

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Complexity Classes

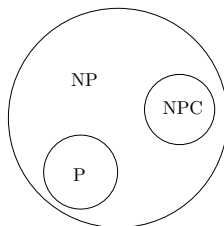
- P:** A decision problem that can be solved in polynomial time.
- NP:** A decision problem that, for an input, can be verified in polynomial time.

NP-Completeness

An important question

Whether $P = NP$ or $P \neq NP$?

NP-Complete Class: A class of decision problems in NP such that if one of them can be solved in polynomial time, all other problems can also be solved in polynomial time.



NP-Complete Problems

- Circuit satisfiability,
 - 3-SAT (satisfiability where the expression is in CNF, and each clause is of length at most 3),
 - Clique decision problem,
 - Vertex Cover decision,
 - Travelling salesman problem,
 - Knapsack problem,
 - Bin packing
 - Art gallery problem
- to name only a few.

Handling the NP-Hard Problems

Brute-force algorithm

Design a clever enumeration strategy, so that

- it guarantees the optimality of the solution, but
- no guarantee on the running time.

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Heuristic

Develop an intuitive algorithm, such that

- it guarantees to run in polynomial time, but
- no guarantee on the quality of the solution.

Approximation Algorithm

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- Guaranteed to run in polynomial time, and
- guaranteed to produce a "high quality" solution.

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But, what is a high quality solution?

Is the solution $= OPT + \alpha$, or
 $\alpha \times OPT$, or
 $(1 + \epsilon) \times OPT$

where,

$OPT \rightarrow$ the optimum solution,

$\alpha \rightarrow$ a constant,

$\epsilon \rightarrow$ a very small constant.

Approximation Algorithm

Note: Designing approximation algorithm for a problem having polynomial time algorithm is also relevant if the time complexity of the problem is very high.

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Difficulty: One needs to prove that the solution is close to optimum, without knowing the optimum solution.

Approximation Algorithm

$f(n)$ -approximation Algorithm

Let P be a problem of size n . An algorithm \mathcal{A} for a problem P is said to be an $f(n)$ -approximation algorithm if and only if for every instance I of P , $|\mathcal{A}(I) - OPT|/OPT \leq f(n)$. It is assumed that $OPT \geq 0$.

Note: $f(n)$ can be a constant also.

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Performance ratio:

$$f(n) = \begin{array}{ll} \mathcal{A}(I)/OPT & \text{in case } P \text{ is a minimization problem} \\ OPT/\mathcal{A}(I) & \text{in case } P \text{ is a maximization problem} \end{array}$$

We will show the **use of ILP** in designing **Approximation Algorithms**

Integer Linear Programming

The Problem

Objective Function: Maximize $8x_1 + 11x_2 + 6x_3 + 4x_4$

Subject to: $5x_1 + 7x_2 + 4x_3 + 3x_4 \leq 14$

$$7x_1 + 2x_3 + x_4 \leq 10$$

$$x_i \in \mathbb{Z}^+ \text{ for all } i = 1, 2, 3, 4$$

Vertex Cover Problem

Input: $G = (V, E) \rightarrow$ a graph, where each vertex is associated a positive weight.

Output: A subset $C \subseteq V$ such that every edge $e \in E$ is covered by some vertex in C , and $w(C)$ is minimized.

ILP Formulation

Minimize: $\sum_{v \in V} w_v x_v$
 Subject to: $x_u + x_v \geq 1$ for each edge $e = (u, v) \in E$
 $x_v \in \{0, 1\}$ for all $v \in V$

LP Relaxation

Minimize: $\sum_{v \in V} w_v x_v$
 Subject to: $x_u + x_v \geq 1$ for each edge $e = (u, v) \in E$
 $0 \leq x_v \leq 1$ for all $v \in V$

This LP can be solved in polynomial time

Let the optimum solution be OPT_f

Vertex Cover Problem

Finally, round the fractional solution x to an integer solution

$$x^* : C = \{v \mid x_v \geq \frac{1}{2}\}$$

Observation 1

C is a **feasible solution** of the **vertex cover problem**.

Follows from the fact: every edge $e = (u, v)$ satisfies $x_u + x_v \geq 1$

Observation 2

$$w(C) \leq 2OPT_f \leq 2OPT$$

$$\begin{aligned} w(C) &= \sum_{v \in C} w(v) \\ &= \sum_{v \in V \mid x_v \geq 1/2} w(v) \\ &\leq 2 \times \sum_{v \in V \mid x_v \geq 1/2} w(v)x(v) \\ &\leq 2 \times \sum_{v \in V} w(v)x(v) \\ &= 2OPT_f \leq 2OPT. \end{aligned}$$

Integrality Gap

Given a set of instances \mathcal{I} of the problem P

The integrality gap is defined by

$\sup_{I \in \mathcal{I}} \frac{OPT(I)}{OPT_f(I)}$ for minimization problem, and $\inf_{I \in \mathcal{I}} \frac{OPT(I)}{OPT_f(I)}$ for maximization problem.

Note: We can not get an approximation factor better than the integrality gap.

Integrality Gap

Vertex cover problem has integrality gap $2 - \frac{2}{n}$

- Let G be a complete graph with n vertices
- $OPT_f = \frac{n}{2}$
- However, the optimum solution of the vertex cover problem is $n - 1$

Thus, the **Integrality Gap** is $\frac{n-1}{n/2} = 2 - \frac{2}{n}$

Our approximation bound is **Tight**

- Consider a bipartite graph $G = (V_1 \cup V_2, E)$
- Solve the corresponding LP and OPT_f satisfies $x_v = 1/2$ for all $v \in V$
- This implies, **the solution of our Heuristic is n**
- But, $OPT = \frac{n}{2}$

Set Cover - Randomized Rounding

Set Cover Problem

Input: A universe of elements $U = \{u_1, u_2, \dots, u_n\}$,
 a family of subsets $\mathcal{T} = \{S_1, S_2, \dots, S_m\}$, and
 a cost function $c : \mathcal{T} \rightarrow \mathbb{R}^+$

Objective: To find a collection of subsets that cover all the elements in

ILP Formulation

Minimize: $\sum_{S \in \mathcal{T}} c(S)x_S$

Subject to: $\sum_{S: e \in S} x_S \geq 1$ for each element $e \in U$
 $x_S \in \{0, 1\}$ for all $S \in \mathcal{T}$

Set Cover - Randomized Rounding

LP Relaxation

$$\begin{array}{ll} \text{Minimize:} & \sum_{S \in \mathcal{T}} c(S)x_S \\ \text{Subject to:} & \sum_{S: e \in S} x_S \geq 1 \text{ for each element } e \in U \\ & 0 \leq x_S \leq 1 \text{ for all } S \in \mathcal{T} \end{array}$$

Let x^* be the optimum solution of the LP.

- Unlike the case of vertex cover, we cannot round x_i^* to its nearest integer.
Reason: If an element u belongs to 100 sets, it could be that $x_i = 1/100$ for each of those sets, and we would be rounding all those numbers to zero, leaving the element u not covered.
- However, if we know that every element u belongs to at most k sets, then we can round the numbers $\geq 1/k$ to 1, and the numbers $< 1/k$ to zero.

Set Cover - Randomized Rounding

- This would give a feasible cover, and we can prove that we achieve a k -approximation.
- Unfortunately, k could be very large, even $n/2$. So, a k -factor approximation is not desirable.

We try to have an approximation guarantee that is never worse than $O(\log n)$.

Set Cover - Randomized Rounding

Assume S is included in the set-cover with probability x_S .

Thus, Expected Cost $E(\text{cost}) = \sum_{S \in \mathcal{T}} c(S)x_S = OPT_f$

Remark: No guarantee that the solution obtained is feasible.

Result

The randomized rounding covers each element with probability at least $1 - \frac{1}{e}$.

Proof:

- Consider an element a , which can be covered by k sets.
- Each of which is selected in the algorithm with probability p_1, p_2, \dots, p_k
- Thus, $\sum_{i=1}^k p_i \geq 1$
- $\text{Prob}[a \text{ is not covered}] = \prod_{1 \leq i \leq k} (1 - p_i) \leq (1 - \frac{1}{k})^k \leq \frac{1}{e}$.
- $\text{Prob}[a \text{ is covered}] = 1 - \frac{1}{e}$

Set Cover - Randomized Rounding

We repeat this procedure $d \log n$ time, and report the union of set covers.

Now, we have

- $\text{Prob}[a \text{ is not covered}] = \left(\frac{1}{e}\right)^{d \log n} \leq \frac{1}{4n}$, for some appropriate choice of d
 - $\text{Prob}[\text{at least one element is not covered}] \leq \frac{1}{4}$, by applying union bound
- $\Rightarrow \text{Prob}[\text{every element is covered}] \geq \frac{3}{4}$
- Total expected cost $E[\text{cost}] = d \log n \times OPT_f$
 - Now, applying Markov inequality, we have

$$\text{Prob}[\text{cost} > 4d \log n \times OPT_f] \leq \frac{d \log n \times OPT_f}{4d \log n \times OPT_f} = \frac{1}{4}$$

- $\text{Prob}[\text{cost} \leq 4d \log n \times OPT_f] \geq \frac{3}{4}$

Set Cover - Randomized Rounding

Problems in this method

- Solution might be infeasible
- Solution may be of very high cost

However, probability of both these events is upper bounded by $\frac{1}{4}$.
Implying, their union is upper bounded by $\frac{1}{2}$.

Result

With probability at least $\frac{1}{2}$, one can get $4d \log n$ -approximation of the set cover problem using $d \log n$ iteration of randomized rounding.

Set Cover - Randomized Rounding

A feasible algorithm

Repeat the iterations until both the conditions (feasibility and targetted cost) are satisfied.

- This may not terminate in polynomial time.
- Although the expected running time is polynomial.
- This class of algorithms belong to the complexity class ZPP , which consists of all languages which can be decided in expected polynomial time.

Set Cover - Randomized Rounding

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Integrality Gap of LP-relaxation for Set Cover

$$\text{Sup}_G \frac{OPT(G)}{OPT_f(G)} \leq 4d \log n$$

Rectangle Stabbing Problem¹

Problem Statement:

Given a set \mathcal{R} of n axis-parallel rectangles, find the minimum number of axis-parallel lines to stab all the members in \mathcal{R} .

A rectangle $r \in \mathcal{R}$ is given using a pair of coordinates $[(a, b), (c, d)]$ corresponding to its (bottom-left, top-right) diagonal.

For the sake of simplicity, we assume that the coordinates are integer valued.

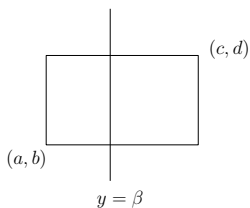
¹Gaur, Ibaraki and Krishnamurthy, J. of Algorithms, 2002 

Rectangle Stabbing Problem

Definition

An axis-parallel (horizontal/vertical) line ℓ stabs a rectangle $r = [(a, b), (c, d)] \in \mathcal{R}$ if ℓ passes through the interior of the rectangle r . if

Example:



**Here the line $y = \beta$ stabs the rectangle.
This implies $a + 1 \leq \beta \leq c - 1$**

Status of the Problem and Our Objective

Status:

The problem is NP-hard

Reference: Hasin and Megiddo, Discrete Appl. Math., 1991

Objective: To design a constant factor approximation algorithm

Result available:

A 2-factor approximation algorithm that runs in $O(n^5)$ time.

Tools used: LP-relaxation.

Integer Programming Formulation

Solution Space: $H \cup V$.

- H – Set of $2n$ horizontal lines at $y = b_i + \epsilon$ and $y = d_i - \epsilon$, where b_i and d_i are y -coordinates of bottom and top boundaries of i -th rectangle.
- V – Set of $2n$ vertical lines at $x = a_i + \epsilon$ and $x = c_i - \epsilon$, where a_i and c_i are x -coordinates of left and right boundaries of i -th rectangle.

Take $4n$ decision variables, namely $x_1, x_2, \dots, x_{2n}, y_1, y_2, \dots, y_{2n}$.

x_i – corresponds to i -th vertical line, and

y_j – corresponds to j -th horizontal line.

These decision variables can assume values 0 and 1 only.

Integer Programming Formulation

H_k – Set of horizontal lines that stab the rectangle r_k , and

V_k – Set of vertical lines that stab the rectangle r_k .

Integer Programming Problem – P

Objective Function:

$$\min \sum_{i \in V} x_i + \sum_{j \in H} y_j$$

Constraints:

For each rectangle r_k , $k = 1, 2, \dots, n$, we have the constraint

$$\sum_{i \in V_k} x_i + \sum_{j \in H_k} y_j \geq 1$$

$$x_i \in [0, 1], \quad \text{for all } i = 1, 2, \dots, 2n, \text{ and}$$

$$y_j \in [0, 1], \quad \text{for all } j = 1, 2, \dots, 2n.$$

LP Relaxation

Linear Programming Problem – \bar{P}

Objective Function:

$$\min \sum_{i \in V} x_i + \sum_{j \in H} y_j$$

Constraints:

$$\sum_{i \in V_k} x_i + \sum_{j \in H_k} y_j \geq 1, \quad \text{for all } k = 1, 2, \dots, n$$

$$x_i \geq 0, \quad \text{for all } i = 1, 2, \dots, 2n, \text{ and}$$

$$y_j \geq 0, \quad \text{for all } j = 1, 2, \dots, 2n.$$

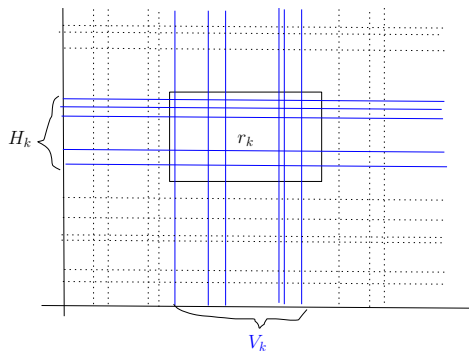
Analysis of LP Solution

Let $\bar{x}_i, i = 1, 2, \dots, 2n$ and $\bar{y}_j, j = 1, 2, \dots, 2n$
be an optimal fractional solution of the LP problem \bar{P} .

For each rectangle $r_k, k = 1, 2, \dots, n$, we have

either $\sum_{i \in V_k} \bar{x}_i \geq \frac{1}{2}$

or $\sum_{j \in H_k} \bar{y}_j \geq \frac{1}{2}$.



Analysis of LP Solution

Let R_H be the set of all k such that $\sum_{i \in V_k} \bar{x}_i \geq \frac{1}{2}$, and

R_V be the set of all k such that $\sum_{j \in H_k} \bar{y}_j \geq \frac{1}{2}$.

Implication:

- The set of rectangles in R_H will be stabbed by horizontal lines, and
- The set of rectangles in R_V will be stabbed by vertical lines.

Thus, we have the following two problems

P_H : Compute the minimum clique cover of an interval graph with the vertical intervals corresponding to the rectangles in R_H , and

P_V : Compute the minimum clique cover of an interval graph with the horizontal intervals corresponding to the rectangles in R_V .

P_H and P_V can be optimally solved in polynomial time.

Analysis of Approximation Factor

Let

Q : Optimum solution of the integer programming problem P ,

\hat{Q} : Optimum solution of the linear programming problem \hat{P} ,

Q_H : Optimum solution of the clique cover problem P_H ,

Q_V : Optimum solution of the clique cover problem P_V .

Theorem

$$Q_H + Q_V \leq 2Q.$$

Analysis of Approximation Factor

Proof: Let $\hat{Q} = (\hat{x}, \hat{y})$ be an optimal fractional solution of \hat{P}
 $\implies Q_V^* = 2\hat{x}$ and $Q_H^* = 2\hat{y}$ are feasible solutions of P_H and P_V .

Reason: For every $k \in R_H$, we have $\sum_{i \in H_k} \hat{y}_i \geq \frac{1}{2}$
 $\implies \sum_{i \in H_k} 2\hat{y}_i \geq 1$.

We have,

- $Q_H + Q_V \leq Q_H^* + Q_V^*$
 [since Q_H and Q_V are optimum solutions and Q_H^* and Q_V^* are feasible solutions of the same minimization problems.]
- $Q_H^* + Q_V^* = 2(\hat{x} + \hat{y}) = 2\hat{Q}$.
- $\hat{Q} \leq Q$
 [Since optimum solution of an LP minimization problem is less than the optimum solution of its corresponding IP problem]

Thus, we have the proof of the result.

Uncapacitated Facility Location

The Problem

Input:

- A set V of demand location,
- a set F of facility location,
- a cost function $c : (V \cup F) \times (V \cup F) \rightarrow Q^+$,
- cost f_j of opening a facility $j \in F$, and
- a demand d_i of client $i \in V$

Goal

- To find a subset $S \subseteq F$
such that $\sum_{j \in S} f_j + \sum_{i \in V} c_{i\sigma_i} d_i$ is minimized.

Uncapacitated Metric Facility Location

Metric Condition $c_{ij} = c_{ji}$, $c_{ij} \leq c_{ik} + c_{kj}$, $c_{ii} = 0$

- There is a bound on total demand (or the no. of clients) a facility can serve, and ,
- There is a bound on the number of facilities that can be opened.

STATUS: NP-COMPLETE

ILP Formulation

For any $j \in F$, define a variable y_j , where

$$\begin{aligned} y_j &= 1 && \text{if facility } j \text{ is opened,} \\ &= 0 && \text{otherwise} \end{aligned}$$

Assumption: A client is assigned to its nearest facility

For each client $i \in V$, $\sigma(i) =$ nearest j such that $y_j = 1$

Define $x_{ij} = 1$ if $i \in V$ is served by $j \in F$
 $= 0$ otherwise

The ILP

Minimize $\sum_{j \in F} f_j y_j + \sum_{i \in V} x_{ij} c_{ij}$

Subject to

- $x_{ij} \leq y_j$ for all $i \in V, j \in F$
- $\sum_{j \in V} x_{ij} \geq 1$ for all $i \in V$

LP Relaxation

Minimize $\sum_{j \in F} f_j y_j + \sum_{i \in V} x_{ij} c_{ij}$

Subject to

- $x_{ij} \leq y_j$ for all $i \in V, j \in F$
- $\sum_{j \in V} x_{ij} \geq 1$ for all $i \in V$
- $x_{ij}, y_j \geq 0$, for all $i \in V, j \in F$

Suppose $x^*, y^* \rightarrow$ optimum solution for the above LP.

Algorithm

1. Solve the LP. Let (x^*, y^*) be the optimum solution.

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4. Let $i = 1$, $F' = \emptyset$
5. For each client $i \in V'$ do
 - Let $j \in B_i$ with $x_{ij}^* > 0$ and f_j minimum. We set $F' = F' \cup \{j\}$, and $\sigma(i) = j$.
 - Define $N_i = \{r_k \in V' \mid B_i \cap B_k \neq \emptyset\}$
 - For each client k such that $r_k \in N_i$ do $\sigma(k) = j$
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 - If $V' = \emptyset$, Break

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Time Complexity Result

The running time of this algorithm is polynomial in the size of the input.

Approximation Factor

Claim: For all $i \in V$, $\sum_{j \in B_i} y_j^* \geq \frac{1}{2}$

$LP_i = \sum_j x_{ij}^* c_{ij} \rightarrow$ the service cost of client $i \in V$ in the LP solution.

Assume that the claim is not true, i.e., $\sum_{j \in B_i} y_j^* < \frac{1}{2}$.

We have $LP_i \geq \sum_{j \notin B_i} x_{ij}^* c_{ij}$
 $\geq \sum_{j \notin B_i} x_{ij}^* r_i$ (since $c_{ij} > r_i$ for all $j \notin B_i$)
 $= r_i \sum_{j \notin B_i} x_{ij}^*$
 $> \frac{1}{2} r_i$ (since $\sum_{j \in B_i} x_{ij}^* \leq \sum_{j \in B_i} y_j^* < \frac{1}{2}$.)

Thus, $LP_i > \frac{1}{2} r_i = \frac{1}{2} \times 2 \sum_j x_{ij}^* c_{ij} = LP_i \rightarrow$ **Contradiction.**

Approximation factor

Result:

If LP_f = Facility cost of the LP solution = $\sum_{j \in F} f_j y_j^*$, then

$$\sum_{j \in F'} f_j \leq 2 \times LP_f$$

- For each $j \in F'$, let i_j is the client who was considered when j was added in F' .
- Consider the ball B_{i_j}
- Then $\sum_{l \in B_{i_j}} y_l^* f_l \geq \sum_{l \in B_{i_j}} y_l^* f_j = f_j \times \sum_{l \in B_{i_j}} y_l^* \geq \frac{1}{2} f_j$
- Reason $\rightarrow \sum_{l \in B_{i_j}} y_l^* \geq \frac{1}{2}$.

Approximation factor

Adding over all members of F' ,

$$\frac{1}{2} \sum_{j \in F'} f_j \leq \sum_{j \in F'} \sum_{\ell \in B_{i_j}} y_\ell^* f_\ell \leq \sum_{j \in F} f_j y_j^*$$

(since all facilities are selected from non-overlapping balls)

Thus, $\sum_{j \in F'} f_j \leq 2 \times LP_F$.

Approximation factor

Result

If $LP_i = \sum_j x_{ij}^* c_{ij}$ is the service cost of client i in the LP solution, then $c_{i\sigma(i)} \leq 6 \times LP_i$

Consider two possible cases for client i

Case 1: Client i is such that some $j \in B_i$ was selected. Then,

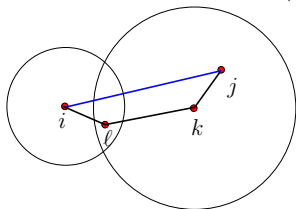
$$c_{i\sigma(i)} \leq r_i = 2LP_i$$

Case 2: Client i is served by a facility $j \in B_k$ chosen for client k since $B_i \cap B_k \neq \emptyset$.

Thus, $\sigma(i) = \sigma(k) = j$

- Surely $r_i > r_k$.
- Let $\ell \in B_i \cap B_k$.
- Thus, $c_{ij} < c_{i\ell} + c_{\ell k} + c_{kj}$
 $\leq r_i + 2r_k \leq 3r_i$ [By triangle inequality]

Thus, $c_{ij} \leq 6LP_i \implies c_{i\sigma(i)} \leq 6LP_i$



Approximation factor

Thus, $\sum_{i \in V} c_i \sigma(i) \leq 6 \times LP_S$,
(LP_S = Service cost of LP Solution)

Theorem

$$\text{Total cost} = \sum_{j \in F'} f_j + \sum_{i \in V} c_i \sigma(i) \leq 6 \times (LP_f + LP_S)$$